# Soft Switching Techniques for High Voltage Gain in Asymmetrical Full Bridge Converter

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**Abstract**—This paper explore the techniques of Asymmetrical full bridge converter with high voltage gain. It achieved zero voltage switching of all power switches, zero current switching of output diodes. Prototype of the converter is developed, experimented and validated using the asymmetrical pulse width modulation techniques. The proposed converter achieved a gain of 12 with zero switching losses, no conduction losses and a fixed switching frequency.

Keywords—Asymmetrical full bridge converter, soft switching, zero voltage switching (ZVS), zero current switching (ZCS).

## I. INTRODUCTION

THE full bridge asymmetrical zero voltage switching is the popular topology for DC DC converters with a fixed switching frequency, zero switching and high gain. The major field of application of these type converters lies in electric vehicle, UPS, fuel cell, photovoltaic system etc [1]. It is used as an intersize system between the low voltage sources and load which requires high voltage conventional boost converters, which were used in these applications have certain drawback like it requires extreme duty cycle to obtain high voltage gain and its voltage gain is limited due to its parasitic components. Another drawback of the conventional boost converters is the reverse recovery problem of the output diodes which degrades the system performances such as efficiency and electric magnetic noises.

High step up DC DC converters using coupled inductors were introduced to overcome the drawback of conventional boost converters. But due to the leakage inductance of the coupled inductor there were parasitic oscillations across the switches and diodes. Galvanic isolation between the input and output stages of these power converters are a major concern about the safety aspects. These high step up DC DC converters are designed as current fed converters. Due to this the voltage stresses of the switches are severe and hence active snubbers are used to clamp the voltage across the switches and to provide zero voltage switching (ZVS) [2]. But the presence of these active snubbers requires additional switches and hence causes additional conduction losses and thus a decrease in the system frequency.

Voltage-fed converters such as phase-shift full-bridge (PSFB) converters [3], are the solutions to overcome the drawback of current fed converters. The problem of high voltage stress across the switches and diodes are eliminated here and hence zero voltage switching is achieved. But here also exist drawback like large conduction loss due to circulating current, duty cycle loss and voltage spikes across output rectifiers. Even though auxiliary snubber circuits can be used to overcome the problem of large voltage spikes of the output rectifiers, the complexity and the overall cost are increased and system efficiency decreased due to additional circuits.

Overall system efficiency can be increased by using Asymmetrical Pulse Width Modulation (APWM) technique [4]. Here the advantages are zero switching loss, no conduction loss penalty and fixed switching frequency. But again drawback exist like the maximum duty cycle is limited to 0.5 and it require large turns ratio of transformer. Later APWM control scheme for the asymmetrical full-bridge converter was introduced without considering the transformer turns ratio. These were also called buck type converters but they are not suitable for step up applications.

As a solution to the entire problems asymmetrical full bridge converter is proposed. This asymmetrical pulse width modulation technique have advantages like high voltage gain with fixed switching frequency, soft switching operation of all power switches and diodes and clamped voltage power switches and output diodes. There is no reverse recovery problem of the output diodes and limitation of maximum duty cycle disappears.

## II. CIRCUT DESCRIPTION

The block diagram representation of the proposed converter is shown in Fig. 1.



Fig. 1. Block diagram representation of the proposed converter

It consist of 4 blocks namely i) input D.C supply in which a 48 volt supply is given ii) inverter circuit which converts D.C to A.C iii) transformer is used here to step up the voltage along with the voltage doubler circuit iv) voltage doubler circuit and v) pulse generation part.

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## Fig. 2. Circuit diagram

The circuit diagram of the proposed converter with highvoltage gain is shown in Fig. 2. The converter consists of four switches  $S_1$  through  $S_4$ . The voltages across the switches  $S_1$ and S<sub>2</sub> in the first bridge are confined to the input voltage V<sub>in</sub>. The clamping capacitor C<sub>c</sub> can clamp the voltages across the switches S<sub>3</sub> and S<sub>4</sub> in the second bridge. The output stage consist of a voltage doubler structure that consists of the secondary winding N<sub>2</sub> of the transformer T, the serial inductor  $L_s$ , the output capacitors  $C_{o1}$  and  $C_{o2}$ , and the output diodes D<sub>01</sub> and D<sub>02</sub>. According to the voltage doubler structure, the voltage gain increases and the voltage stresses of the output diodes are confined to the output voltage Vo without any auxiliary circuits. The transformer T is modeled as the magnetizing inductance L<sub>m</sub> and the ideal transformer that has a turns ratio of 1:n (n=N<sub>2</sub>/N<sub>1</sub>). Its leakage inductance is included in the serial inductor  $L_s$ . The voltage across the capacitance  $C_{01}$ in the secondary side is Vo1 and the voltage across the capacitance  $C_{o2}$  is  $V_{o2}$ . The output voltage is the sum of  $V_{o1}$ and Vo2.

The main advantages of the proposed converter include the elimination of switching losses and it maintains low conduction loss and improves the efficiency. It provides high voltage gain at fixed switching frequency. It allows the soft switching operations [5]-[6] of all power switches and diodes thus reverse recovery problem is alleviated due to an additional inductor in the secondary side of the transformer.

## III. MODAL ANALYSIS

The operations of the proposed converter during switching period Ts are divided into four modes and that can be explained with the help of Fig. 3.



Fig. 3. Theoretical waveforms

*Mode* 1  $[t_0, t_1]$ :



Fig. 4. Mode 1 operation

Mode 1 operation of the proposed converter is shown in Fig. 4. The voltages across the parasitic capacitances  $C_1$  through  $C_4$  are  $V_{S1}$ ,  $V_{S2}$ ,  $V_{S3}$  and  $V_{S4}$ . At  $t_0$ , the switches  $S_2$  and  $S_3$  are turned OFF. Then, the energy stored in the magnetic components starts to charge/discharge the parasitic capacitances  $C_1$  through  $C_4$ . Therefore, the voltages across  $C_2$  and  $C_3$  start to rise from zero and the voltage  $V_{S4}$  starts to fall from  $(V_{in}+V_c)$  and the voltage  $v_{S1}$  starts to fall from  $V_{in}$ . When the voltages  $v_{S1}$  and  $v_{S4}$  arrive at zero, their body diodes  $D_1$  and  $D_4$  are turned ON. Then, the gate signals are applied to the switches  $S_1$  and  $S_4$ . Since the currents have already flown through  $D_1$  and  $D_4$  and the voltages  $V_{S1}$  and  $V_{S4}$  are clamped as zero before the switches  $S_1$  and  $S_4$  are turned ON, zero-

voltage turn-ON of  $S_1$  and  $S_4$  is achieved. With the turn-ON of  $S_1$  and  $S_4$ , the primary voltage  $v_p$  across  $L_m$  is  $V_{in}$ . Then, the magnetizing current  $I_m$  increases linearly from its minimum value  $I_{m2}$  as follows:

$$I_m(t) = I_{m_2} + \frac{V_{in}}{L_m}(t - t_0)$$
(1)

Since the voltage  $V_{Ls}$  across Ls is  $nV_{in}+V_{o1}$ , the secondary current  $i_s$  increases from its minimum value  $-I_{Do1}$  as follows:

$$\dot{i}_{s}(t) = -\dot{i}_{Dol} + \frac{nV_{in} + V_{o1}}{L}(t - t_{0})$$
<sup>(2)</sup>

*Mode* 2  $[t_1, t_2]$ :

Mode 2 operation is shown in Fig. 5. At  $t_1$ , the current  $i_s$  and  $i_{D01}$  arrive at zero and the diode  $D_{o1}$  is turned OFF. Then, the output diode  $D_{o2}$  turned ON and its current increases linearly. Since the current changing rate of  $D_{o1}$  is controlled by the serial inductor  $L_s$ , its reverse-recovery problem is significantly alleviated. Since the voltage  $V_{Ls}$  is  $(n V_{in} - V_{o2})$  in this mode, the current  $i_s$  are given by



Fig. 5. Mode 2 operation

*Mode 3* [*t*<sub>2</sub>, *t*<sub>3</sub>]:





Mode 3 operation is shown in Fig. 6. Similar to mode 1, the switches  $S_1$  and  $S_4$  are turned OFF at  $t_2$ . The parasitic capacitors  $C_1$  and  $C_4$  start to be charged from zero and the capacitors  $C_2$  and  $C_3$  start to be discharged from  $V_{in}$  and  $(V_{in}+V_c)$  respectively. When  $C_1$  and  $C_4$  are fully charged and discharged, the voltages  $V_{S2}$  and  $V_{S3}$  become zero and the

body diodes  $D_2$  and  $D_3$  are turned ON and the gate signals are applied to the switches  $S_2$  and  $S_3$ . Since the currents have already flown through  $D_2$  and  $D_3$  and the voltages  $v_{S2}$  and  $v_{S3}$ are clamped as zero, zero-voltage turn ON of  $S_2$  and  $S_3$  is achieved. With the turn-ON of  $S_2$  and  $S_3$ , the voltage  $v_p$  across Lm is -( $V_{in}+V_c$ ). Then, the current  $i_m$  decreases linearly from its maximum value  $I_{ml}$  as follows

$$i_m(t) = I_{m1} - \frac{V_{in} + V_c}{L_m} (t - t_0)$$
(4)

Since the voltage  $v_{Ls}$  across  $L_s$  is -(n ( $V_{in} + V_c$ ) + $V_{o2}$ ), the current is decreases from its maximum value  $I_{Do2}$  as follows:

$$\dot{i}_{s}(t) = -I_{Do2} - \frac{n(V_{in} + V_{c}) + V_{o2}}{L_{s}}(t - t_{2})$$
(5)

*Mode* 4 [*t*<sub>3</sub>, *t*<sub>4</sub>]:

Mode 4 operation of the proposed converter is shown in Fig. 7.



Fig. 7. Mode 4 operation

Similar to mode 2, the currents  $i_s$  and  $i_{Do2}$  arrive at zero and the diode  $D_{o2}$  is turned OFF at  $t_3$ . Then, the output diode  $D_{o1}$  is turned ON and its current increases linearly. Since the current changing rate of  $D_{o2}$  is controlled by  $L_s$ , its reverserecovery problem is significantly alleviated. Since the voltage  $V_{Ls}$  is  $-(n(V_{in}+V_c)-V_{o1})$ , the current is given by

$$\dot{i}_{s}(t) = -\frac{n(V_{in} + V_{c}) - V_{o1}}{L_{s}}(t - t_{3})$$
(6)

At the end of this mode, the currents  $i_m$  and  $i_s$  arrive at  $I_{m2}$  and  $-I_{Dol}$ , respectively.

### IV. DESIGN PARAMETERS

## A. Clamping Capacitor Voltage (V<sub>c</sub>)

Referring to the voltage wave form  $V_p$  in Fig. 3, the volt-second balance law gives

$$V_{in}DT_s + (V_{in} + V_c)(1 - D)T_s = 0$$
(7)

B. Voltage Gain

The diode currents I<sub>Do1</sub> can be written as

$$I_{D_{01}} = \frac{nV_{in} + V_{o1}}{L_s} d_1 T_s \tag{8}$$

The voltage Vo1 is obtained by

$$V_{o1} = \frac{D - d_1 - (\frac{D}{1 - D})d_2}{1 - D + d_1 - d_2} nV_{in}$$
(9)

Maximum diode current  $I_{Do2}$  can be written as follows:

$$I_{Do2} = \frac{nV_{in} - V_{o2}}{L_s} (D - d_2)T_s$$
(10)

Voltage Vo2 can be obtained by

$$V_{o2} = \frac{D - d_1 - (\frac{D}{1 - D})d_2}{D - d_1 + d_2} nV_{in}$$
(11)

The average values of the diode currents  $i_{Do1}$  and  $i_{Do2}$  are equal to the output current  $I_0$  and the following relation can be obtained by

$$I_o = \frac{(1 - D - d_1 - d_2)I_{Dol}}{2}$$
(12)

From (8) and (12),  $d_1$  and  $d_2$  is obtained by,

$$d_1 = kD \tag{13}$$

$$d_2 = k(1-D)$$
 (14)

$$k = (1 - \sqrt{1 - \frac{8L_s I_0}{nDV_{in}T_s}})$$
(15)

$$M = \frac{V_0}{V_{in}} \tag{16}$$

C. Maximum and Minimum Values of the Magnetizing Current (im)

In modes 3 and 4, the switch current  $i_{S3}$  is flowing through the clamping capacitor  $C_c$ . Since the average capacitor current must be zero under a steady-state condition, the average value of  $i_{S3}$  is zero. The maximum value  $I_{m1}$  and the minimum value  $I_{m2}$  are given by

$$I_{m_{1}} = I_{in} + \frac{V_{in}DT_{s}}{2L_{m}}$$
(17)

$$I_{m_2} = I_{in} - \frac{V_{in}DT_s}{2L_m}$$
(18)

## D. ZVS Conditions for the Switches S1 through S4

From Fig. 3, there is no current cancellation between  $i_p(=ni_s)$  and  $i_m$  at  $t_2$ . Therefore, for ZVS of  $S_2$  and  $S_3$ , the total energy stored in  $L_m$  and  $L_s$  should be larger than the energy stored in  $C_1$  through  $C_4$ . The following condition should be satisfied:

$$\frac{L_{m}I^{2}_{m1}}{2} + \frac{L_{s}I^{2}_{D0_{2}}}{2} \\
> \frac{(C_{1} + C_{2})V^{2}_{in}}{2} + \frac{(C_{3} + C_{4})(V_{in} + V_{c})^{2}}{2}$$
(19)

On the other hand, there is current cancellation between  $i_p(=ni_s)$  and im at  $t_0$ . Therefore, for ZVS of  $S_1$  and  $S_4$ , the energy difference between the energies stored in Lm and Ls should be larger than the energy stored in  $C_1$  through  $C_4$  as follows:

$$-\frac{L_{m1}I^{2}_{m2}}{2} + \frac{L_{s1}D^{2}_{o1}}{2}$$

$$> \frac{(C_{1} + C_{2})V^{2}_{in}}{2} + \frac{(C_{3} + C_{4})(V_{in} + V_{c})^{2}}{2}$$
(20)

This condition can be used to determine L<sub>m</sub>.

## E. Voltage Stresses of Power Switches and Output Diodes

The voltage stresses of  $S_3$  and  $S_4$  are the sum of the input voltage  $V_{in}$  and the clamping capacitor voltage  $V_c$ . Since the clamping capacitor voltage depends on the duty cycle, the voltage stresses of  $S_3$  and  $S_4$  can be changed according to load. Maximum values of  $V_{S3}$  and  $V_{S4}$  in the second bridge is given by

$$V_{s3,\max} = V_{s4,\max} = V_{in} + V_c = \frac{DV_{in}}{1 - D}$$
(21)

When the duty cycle *D* is below 0.5, the maximum values of  $V_{S3}$  and  $V_{S4}$  are lower than the input voltage  $V_{in}$ . Due to the voltage doubler structure, the maximum values of the voltages across the output diodes are confined to the output voltage  $V_0$ .

#### V. HARDWARE IMPLEMENTATION

In order to verify the validity of the proposed topology, converter prototype is implemented.

TABLE I. PARAMETERS USED

Input Voltage (V <sub>in</sub> )	12 V
Switching Frequency (f <sub>s</sub> )	20 kHz
Maximum Duty Cycle (D <sub>max</sub> )	0.7
Serial Inductor (L <sub>s</sub> )	570 µH
Maximum output power	150W
Clamping Capacitance (C <sub>c</sub> )	22 µF
Values of $C_{o1}$ and $C_{o2}$	220 µF
MOSFET	IRF830

Hardware part of the proposed converter is shown in Fig. 8 and the parameters used for implementation is given in Table I.



Fig. 8. Hardware part

Here AT89C51 is used and it consists of mainly 4 ports P0, P1, P2 and P3 with 8 pins. Two pins of port 1 are taken for the PWM generation. Controller part is given to the driver circuit and here FAN7392 is used.



Fig. 9. Pulses during the ON time Pulses during the ON time are shown in Fig. 9.



Fig. 10. Voltage across the switches

Voltage across the switches are shown in Fig. 10. Thus the voltage across the first waveform is 12.4 and that of second one is 28.4 with the influence of clamping capacitor.



Fig. 12. (a)



Fig. 12. (c)



Fig. 12. (d)

Pulses across each switches is shown in the Fig.12. (a), (b), (c) and (d).



#### Fig. 13. Output voltage

The output voltage is shown in Fig.13 with 145V as output voltage and input as 12V. Hence the voltage gain of the system is calculated as 12 hence the gain is very high.

## VI. CONCLUSION

Asymmetrical full-bridge converter with high voltage gain is proposed in this paper. The ZVS of all power switches and ZCS of the output diodes are achieved. The proposed converter is able to provide high-voltage gain with relatively low transformer turns ratio. Also, without any auxiliary circuits, the voltages across the switches and the output diodes are effectively clamped. Therefore, the proposed converter is suitable for high-voltage applications. The voltage gain is 12 with a transformer turns ratio of 4.5.

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